#### Densest/Heaviest *k*-subgraph on Interval Graphs, Chordal Graphs and Planar Graphs

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#### **Problem Definition:**

Densest k-Subgraph Problem(DS-k):

- Input:G(V, E), k > 0.
- Output: an induced subgraph D s.t. |V(D)| = k.
- Goal:Maximize |E(D)|.

Heaviest k-Subgraph Problem(HS-k):

- Input:G(V, E), $w: E \to R^+$ ,k > 0.
- Output: a induced subgraph D s.t. |V(D)| = k.
- Goal:Maximize  $\sum_{e \in E(D)} w(e)$ .

## **Previous Results**

- NP-hard even on chordal graphs(Corneil,Perl.1984) and planar graphs(Keil,Brecht.1991).
- $n^{\delta}$ -approximation for some  $\delta < 1/3$  (Feige,Kortsarz,Peleg.2001).
- *n*/*k*-approximation(Srivastav,Wolf.1998;Goemans,1999).
- No PTAS in general(Khot.2004).
- PTAS for dense graph(Arora, Karger, Karpinski.1995).

## **Previous Results**

- Some better approximation for special k.
- HS-k is in P on trees(Maffioli.1991), co-graphs(Corneil,Perl.1984) and chordal graph if its clique graph is a path(Liazi,Milis,Zissimopoulos.2004).
- PTAS on chordal graph if its clique graph is a star(Liazi,Milis,Pascual,Zissimopoulos.2006).
- OPEN: complexity on interval graphs(even for proper interval graphs).

#### **Our Results**

- Proper interval graphs(unknown): PTAS.
- Chordal graphs(NP-hard): Constant approximation.
- Planar graphs(NP-hard): PTAS.

Densest disjoint clique *k*-subgraph(DDCS-*k*) problem: Find a (not necessarily induced) subgraph G'(V', E') such that

- |V'| = k;
- G' is composed with several vertex disjoint cliques;
- |E'| is maximized.

DDCS-*k* can be solved by Dynamic Programming: Let DS(i, l) be the optimal solution of DDCS-*l* problem on  $G(V_{1...i})$ .

$$DS(i,l) = \max_{(j,x)\in\mathcal{A}} \{ DS(j,x) + \binom{l-x}{2} \}$$

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where  $\mathcal{A}$  is the feasible integer solution set of the following constraints system:

 $1\leq j < i, 0\leq x \leq l, l-x \leq i-j, l-x \leq i-q_G(i)+1.$ 

An optimal DDCS-k solution is a 3-approximation of DS-k problem. We construct a DDCS-k solution  $OPT_{DDCS}$  from an optimal

solution  $OPT_{DS}$  of the DS-*k* problem such that  $|OPT_{DDCS}| \ge 1/3 \cdot |OPT_DS|$ .

Construction(Greedy):

- Repeatedly remove the vertices and all adjacent edges of a maximum clique from *OPT*<sub>DS</sub>.
- Take  $OPT_{DDCS}$  as the union of these maximum cliques.



**Def:** *overlap number*  $\kappa_G(v)$  as the number of maximal cliques in *G* containing *v*.

The *h*-overlap clique subgraph H is a subgraph of G such that  $\kappa_H(v) \leq h$  for all  $v \in V(H)$ .

For example, a disjoint clique subgraph is a 1-overlap clique subgraph.

## Proper Interval Graphs-PTAS

*densest h*-overlap clique *k*-subgraph(DOCS-(h, k)) problem: Find a (not necessarily induced) subgraph G'(V', E') such that

- |V'| = k;
- G' is a h-overlap clique subgraph of G;
- |E'| is maximized.

 $\mathsf{DOCS-}(h,k)$  can be also solved by dynamic problem if h is a constant.

Similarly, we construct a DOCS-(h, k) solution  $OPT_{DOCS}$  from an optimal solution  $OPT_{DS}$  of the DS-k problem such that  $|OPT_{DOCS}| \ge (1 - \frac{4}{h/2-1}) \cdot |OPT_{DS}|.$ 

So, in order to get a  $1-\epsilon$  approximation, it is enough to set  $h=2+8/\epsilon$ .

# Proper Interval Graphs-PTAS





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A graph is *chordal* if it does not contain an induced cycle of length k for  $k \ge 4$ .

A *perfect elimination order* of a graph is an ordering of the vertices such that Pred(v) forms a clique for every vertex v, where Pred(v) is the set of vertices adjacent to v and preceding v in the order.

**Thm**: A graph is chordal if and only if it has a perfect elimination order.

Maximum Density Subgraph Problem(MDSP)

- Input G(V, E), vertex weight  $w : v \to \mathbb{R}^+$ ,
- Output: an induced subgraph G'(V', E').
- Goal: maximize the density  $\frac{(\sum_{v \in V'} w(v) + |E'|)}{|V'|}$ .

This problem can be solved optimally in polynomial time by reducing to a parametric flow problem [Gallo,Grigoriadis,Tarjan.1989]. Important Fact:  $w(v) + d_{G'}(v) \ge \rho$ .

The high level idea :

We run the above MSDP algorithm on our given graph with w(v) = 0 for all  $v \in V$ 

- we get a subgraph G' of size k, we have exactly an optimal solution for the DS-k problem.
- If we get a smaller subgraph, we repeat the MSDP algorithm in the remaining graph and add the solution in.
- If we we get a larger subgraph, we need to pick some vertices in this subgraph to satisfy the cardinality constraint without losing much density.

#### Densest-k-Subgraph-Chordal(G(V,E))

1: 
$$V_0 = \emptyset; i = 0;$$

2: i = i + 1;run MSDP in the remaining graph

 $G(V - V_{i-1}, E(V - V_{i-1}), w_i(v) = d(v, V_{i-1})$ . let the optimal subgraph(subset of vertices) be  $V'_i$  and the density be  $\rho_i$ .

3: if 
$$|V_{i-1}| + |V'_i| < k/2$$
 then

4: 
$$V_i = V_{i-1} \cup V'_i$$
 and go back to step 2.

5: else if 
$$k/2 \le |V_{i-1}| + |V'_i| \le k$$
 then

$$6: \quad V_i = V_{i-1} \cup V'.$$

7: else if 
$$|V_{i-1}| + |V'_i| > k$$
 then

8: 
$$V'' = Pick(V'_i, w_i)$$
 and  $V_i = V_{i-1} \cup V''$ ;

9: end if

10: Arbitrary take  $k - |V_i|$  remaining vertices into  $V_i$ .

## $\operatorname{Pick}(V'_t, \mathbf{w})$

1: Compute a perfect elimination order for  $V^\prime,\,{\rm say}$ 

$$\{v_1, v_2, \dots, v_m\}, m > k/2. V'' = \emptyset.$$

2: for i=m to 1 do

$$\begin{array}{lll} \textbf{3:} & \text{ if } |Pred_{V_t'}(v_i)| \geq \rho_t/2 \text{ then} \\ \textbf{4:} & \text{ if } |V''| + |Pred_{V_t'}(v_i)| + 1 \leq k/4 \text{ then} \\ \textbf{5:} & V'' = V'' \cup \{v_i\} \cup Pred_{V_t'}(v_i) \ . \\ \textbf{6:} & \text{ else if } k/4 < |V''| + |Pred_{V_t'}(v_i)| + 1 \leq k/2 \text{ then} \\ \textbf{7:} & V'' = V'' \cup \{v_i\} \cup Pred_{V_t'}(v_i); \text{ return } V''. \\ \textbf{8:} & \text{ else if } |V''| + |Pred_{V_t'}(v_i)| + 1 > k/2 \text{ then} \\ \textbf{9:} & \text{ Add into } V'' v_i \text{ and arbitrary its } k/2 - |V''| - 1 \\ & \text{ predecessors; return } V''. \end{array}$$

#### 10: **end if**

11: else if 
$$w(v_i) + |Succ_{V'_t}(v_i)| > \rho_t/2$$
 then

12: 
$$V'' = V'' \cup \{v_i\}; ext{ If } |V''| > k/4 ext{ return } V'';$$

- 13: end if
- 14: end for

Suppose  $OPT = G^*(V^*, E^*)$ .

If  $|E(SOL \cap V^*)| \ge |E^*|/2$ , then the algorithm is a 1/2-approximation.

If not.....

#### Analysis Sketch:

Let  $I_i = V_i \cap V^*$  and  $R_i = V^* \setminus I_i$ . Since we get the the optimal solution  $V'_i$  on MDSP instance  $G(V - V_{i-1}, E(V - V_{i-1}), w_i(v) = d(v, V_{i-1})$  at step *i*, we have

$$\begin{split} \rho_i &= \frac{|E(V_i')| + d(V_{i-1}, V_i')}{|V_i'|} \geq \frac{|E(R_{i-1})| + d(V_{i-1}, R_{i-1})}{|R_{i-1}|} \geq \frac{|E(R_{i-1})| + d(I_{i-1}, R_{i-1})}{|R_{i-1}|} \\ &\geq \frac{|E(R_{i-1})| + d(I_{i-1}, R_{i-1})}{k} = \frac{|E^*| - |E(I_{i-1})|}{k} \geq \frac{|E^*| - |E(I_t)|}{k} \geq \frac{|E^*|}{2k} = \frac{\rho^*}{2}. \end{split}$$

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for all  $i \leq t$ .

we can prove  $\rho_i \ge \rho_{i+1}$  for all i. We can also prove if  $\rho_i > k/4$  then i = 1. If  $\rho_t > k/4$ , and recall  $d_{V_1}(v_1) \ge \rho_1 > k/4$ , So, a clique of size at least k/4, a 16-approximation. If not,...

#### In Pick:

#### we can see

 $w(v) + d_{V''}(v) = w(v) + |Pred_{V''}(v)| + |Succ_{V''}(v)| \ge \rho_t/2.$ 

#### So

# Planar Graph

#### Sketch:

- Decompose the planar graph into a series of *K*-outerplanar graphs.
- Solve the problem in each outerplanar graph.
- Recombine the solution.

Standard Baker's technique, but some more details...omit here.

# Thank You!

 thanks to Jian XIA and Yan ZHANG for discussions on proper interval graphs.